

Deep Learning in Remote Sensing

Yonghao Xu

Computer Vision Laboratory

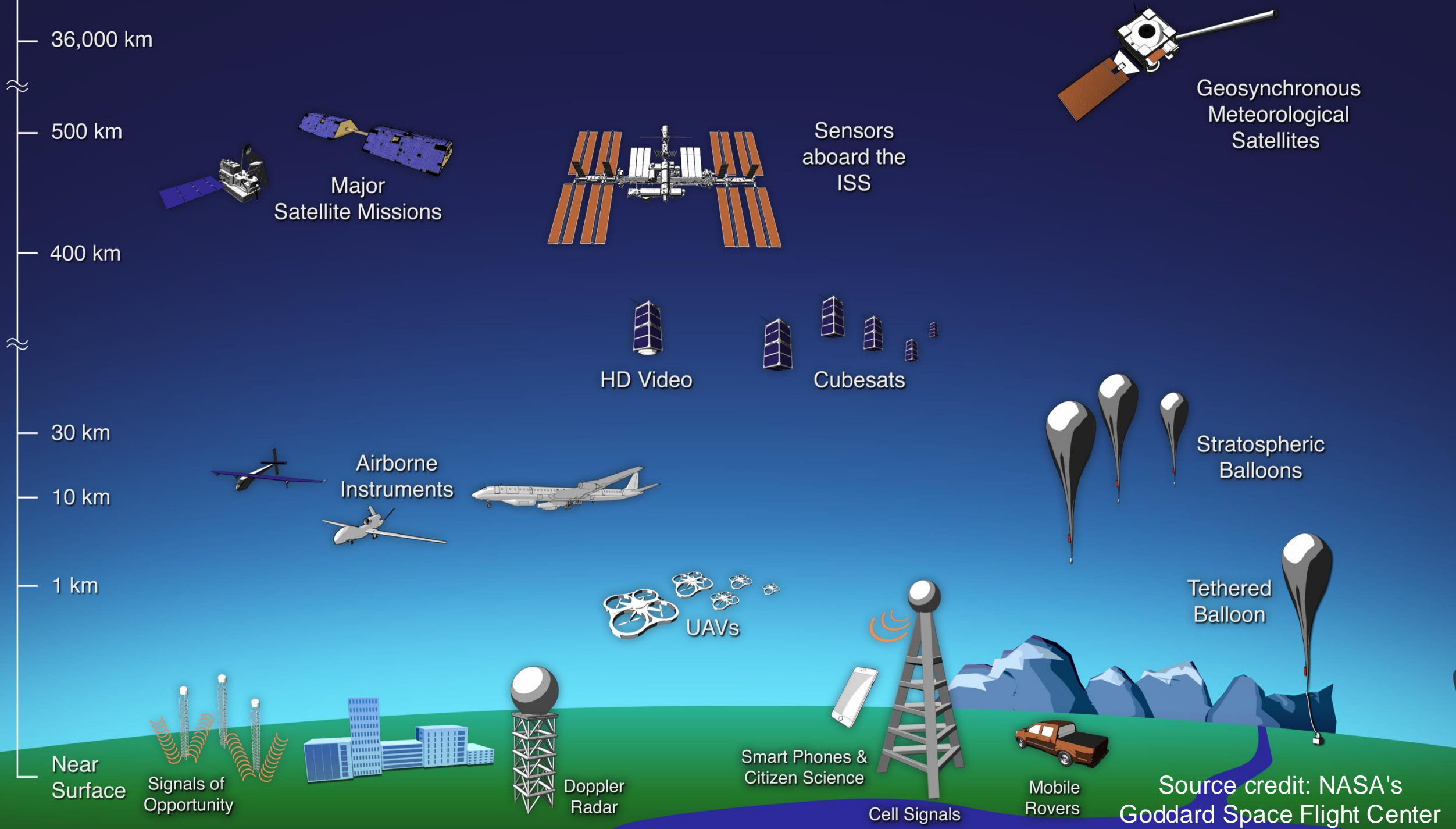
Department of Electrical Engineering

Linköping University

Sensing without physical contact



Source credit: ESA
27-11-2021 04:18 UTC



Middelgrunden, Denmark

1984

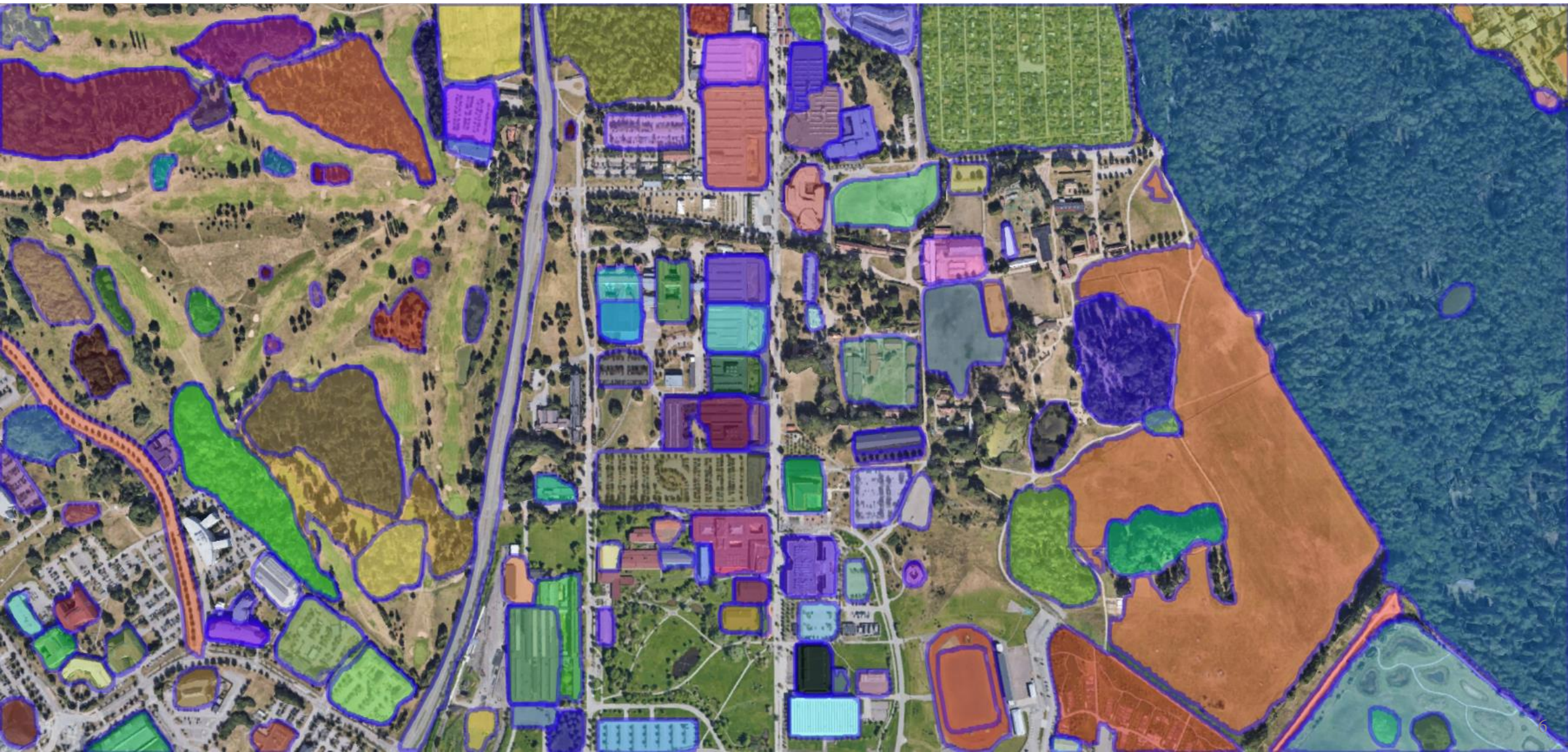


Google Earth Timelapse

From Data to Information

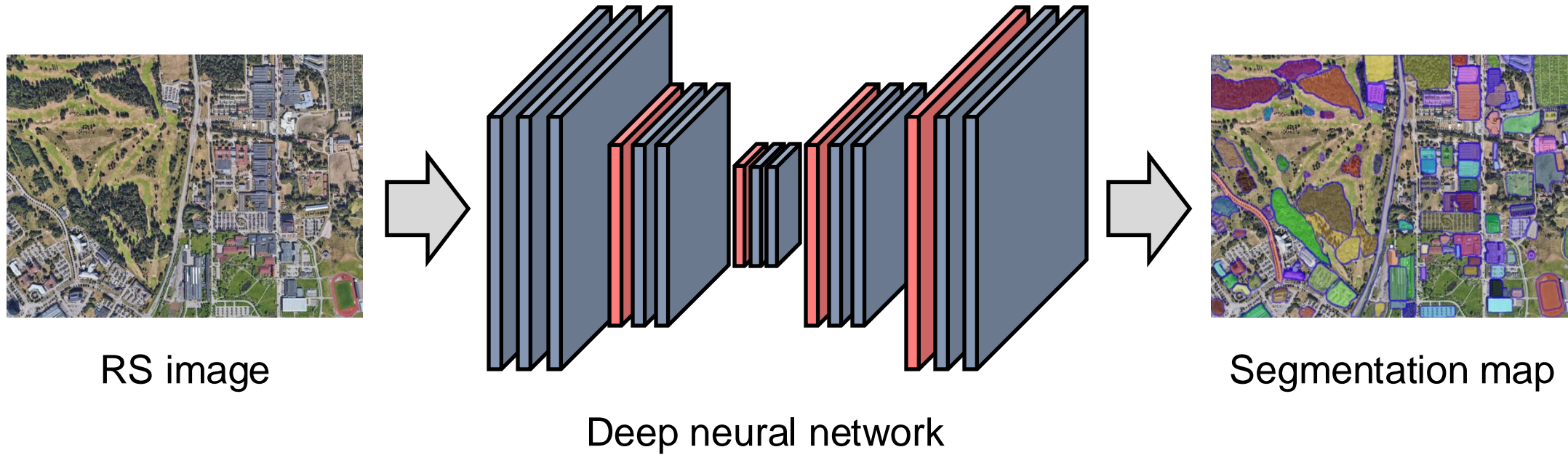


Land Cover Mapping



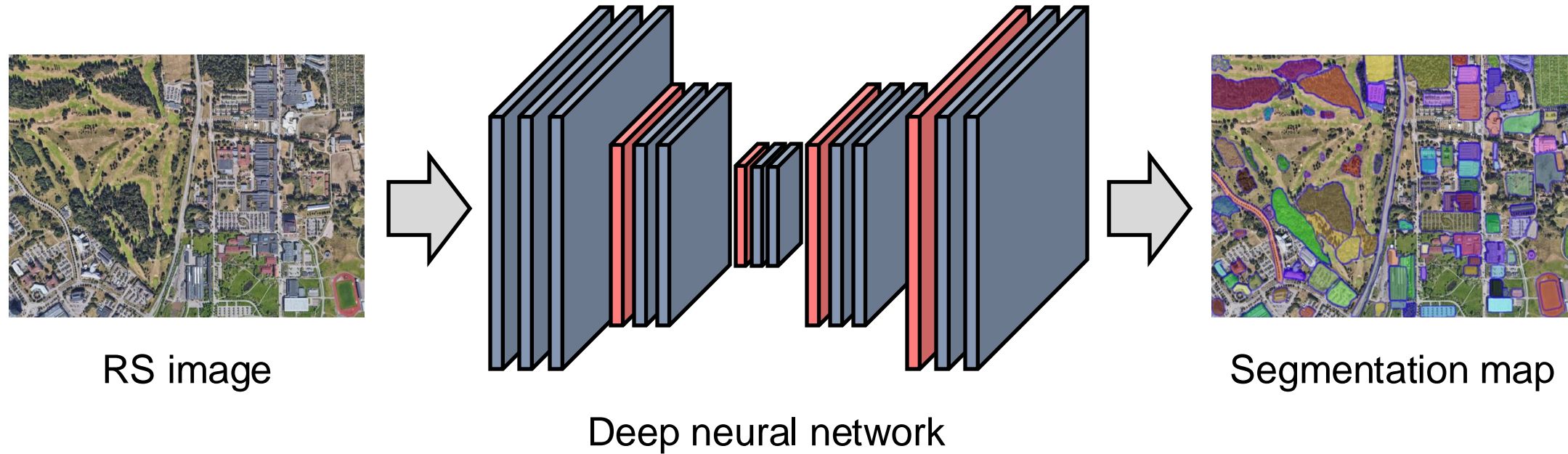
AI-Driven Remote Sensing Data Interpretation

- Data in and insights out



AI-Driven Remote Sensing Data Interpretation

- Data in and insights out



- Challenge

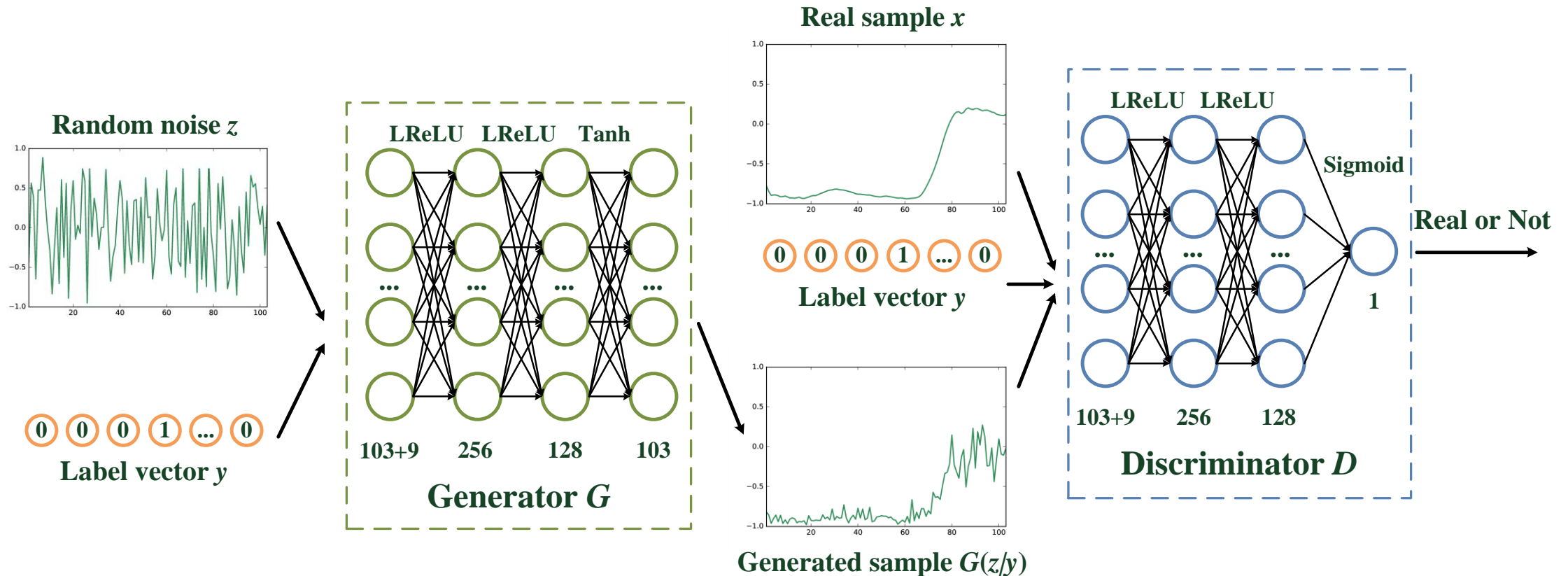
Deep neural networks are **data-hungry**

The collection of high-quality annotations is **time-consuming!**

Unsupervised Learning

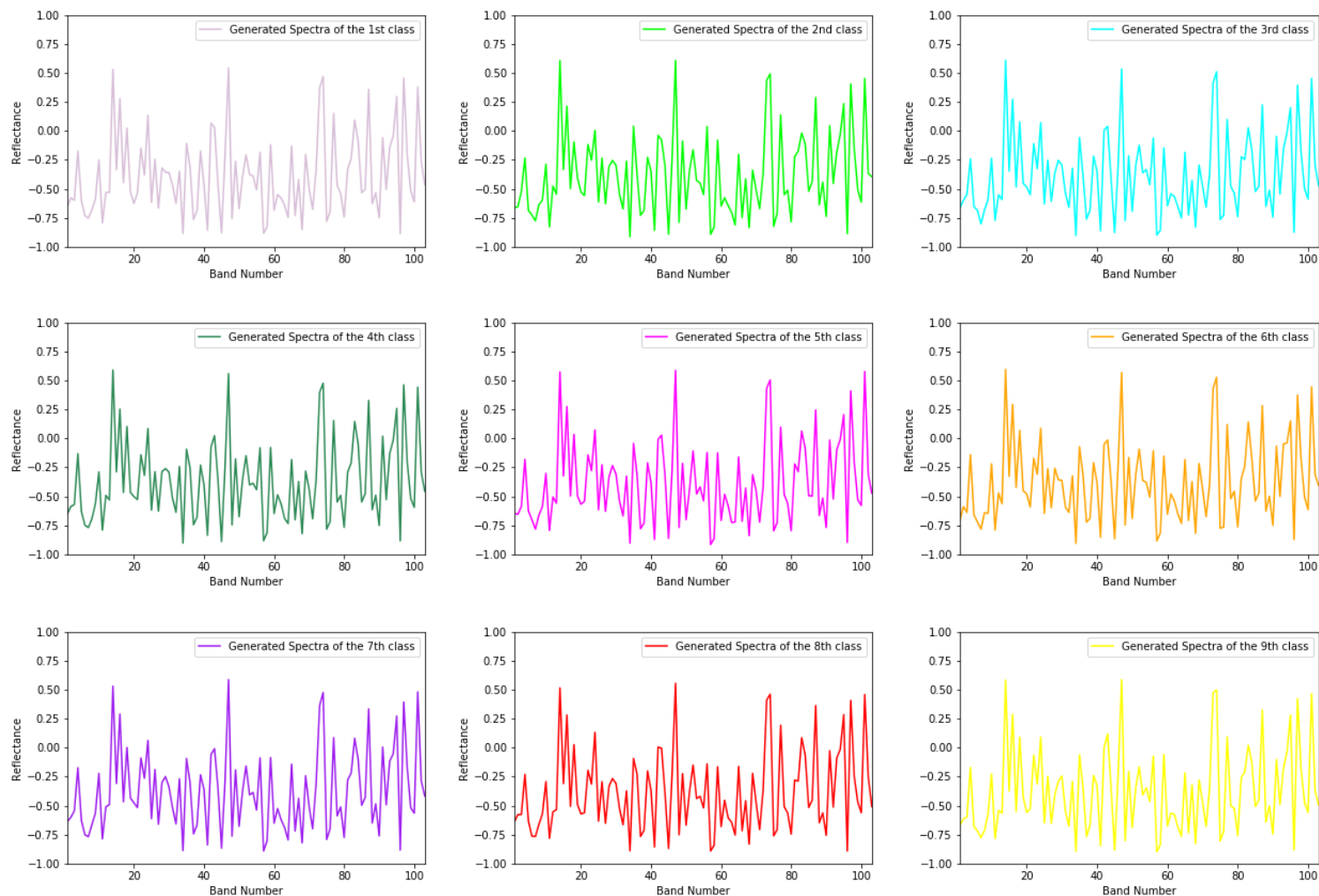
- Spectrum data synthesis with GAN

$$\min_G \max_D V(D, G) = \mathbb{E}_{x \sim p_x(x)} \log D(x|y) + \mathbb{E}_{z \sim p_z(z)} \log (1 - D(G(z|y)))$$



Unsupervised Learning

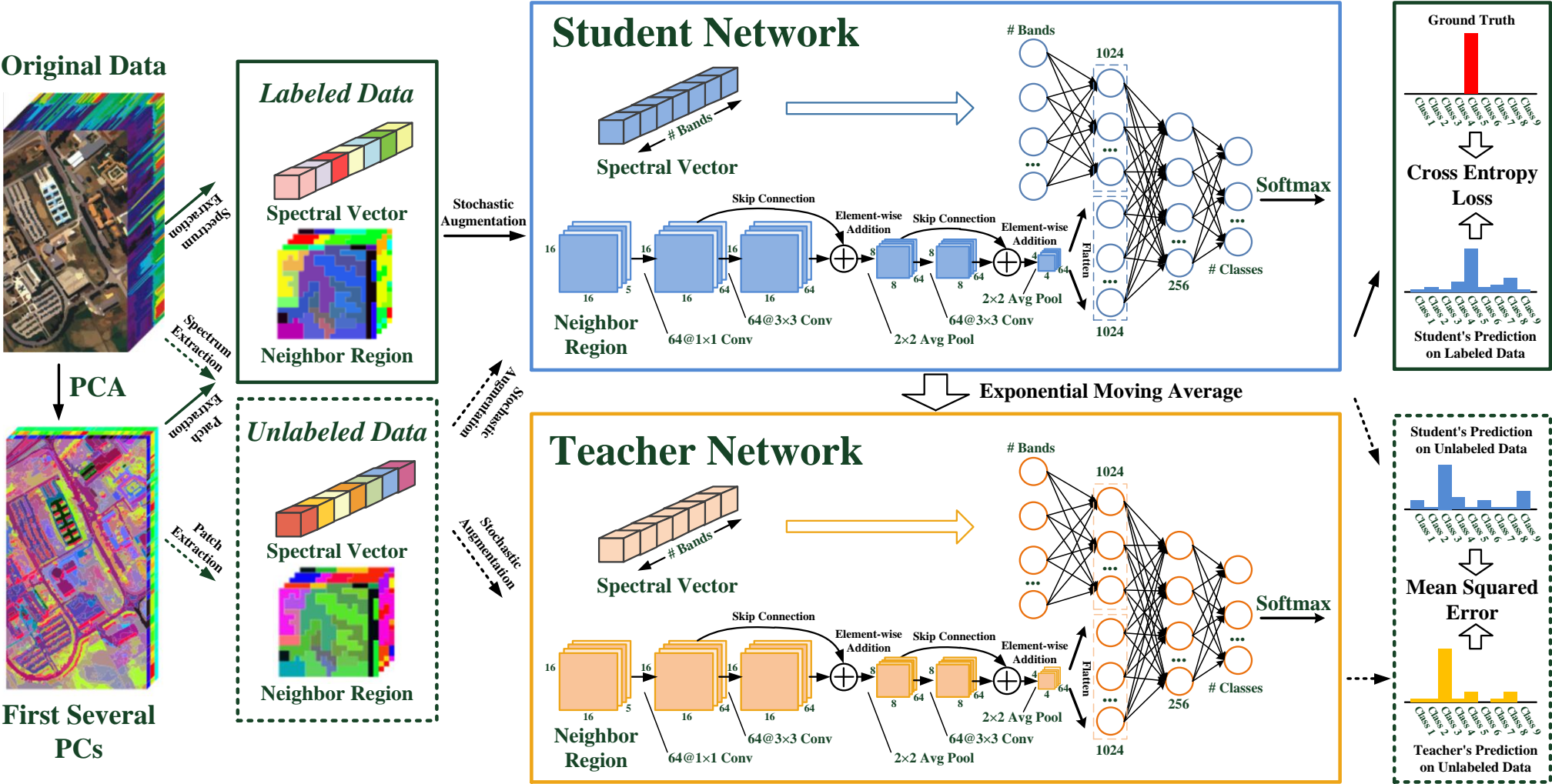
- Spectrum data synthesis with GAN



The first 100 wavebands are reshaped into a 10×10 image for visualization

Semi-supervised Learning

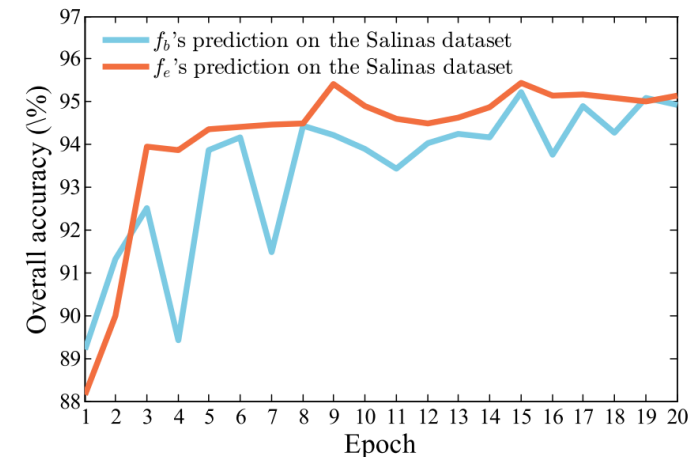
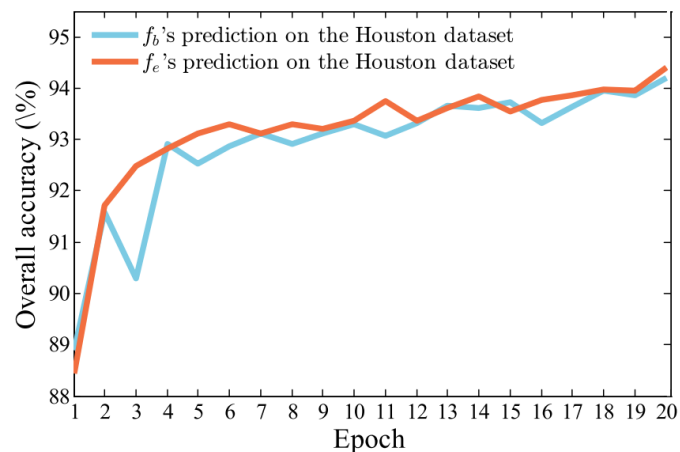
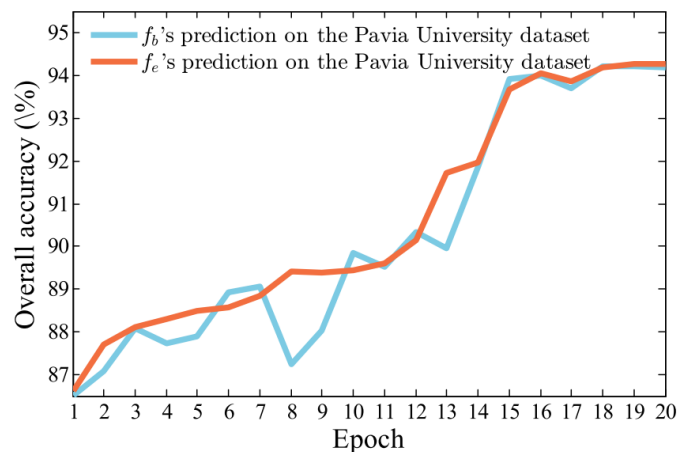
- Learning with unlabeled data



Y. Xu, B. Du, and L. Zhang, "Robust self-ensembling network for hyperspectral image classification," in *IEEE Trans. Neural Netw. Learn. Syst.*, vol. 35, no. 3, pp. 3780-3793, 2022.

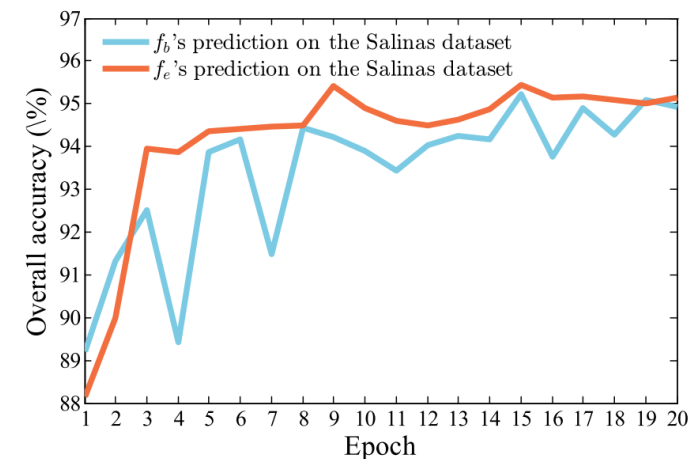
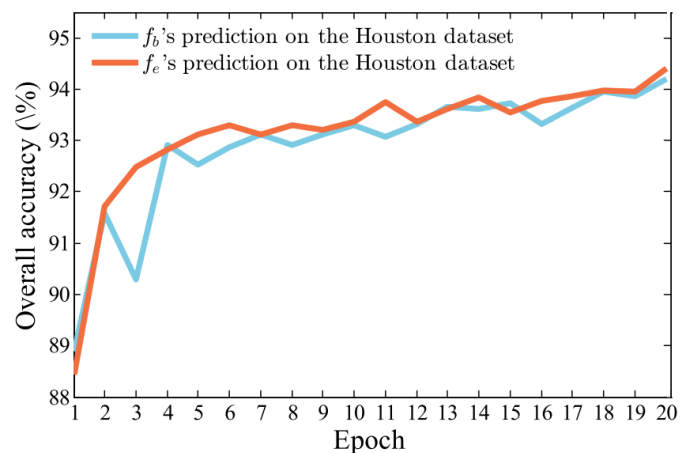
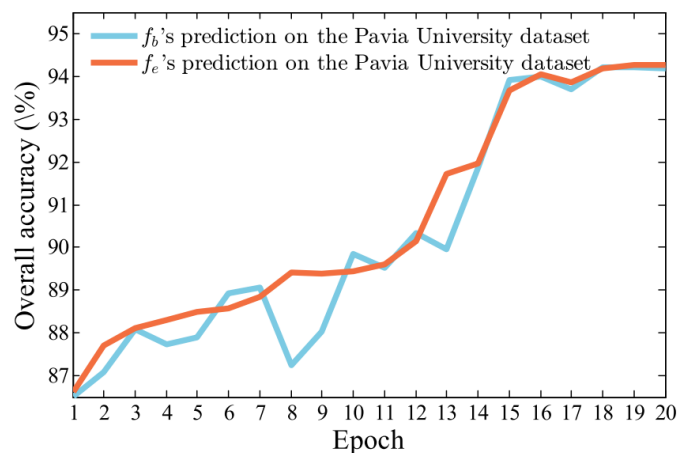
Semi-supervised Learning

- Performance of teacher and student nets over time

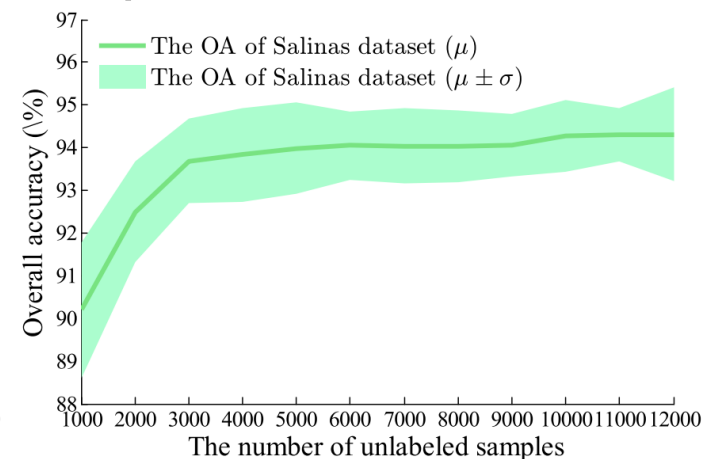
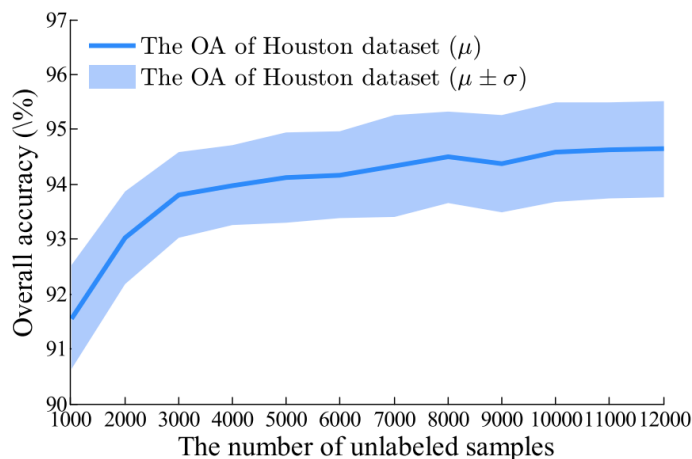
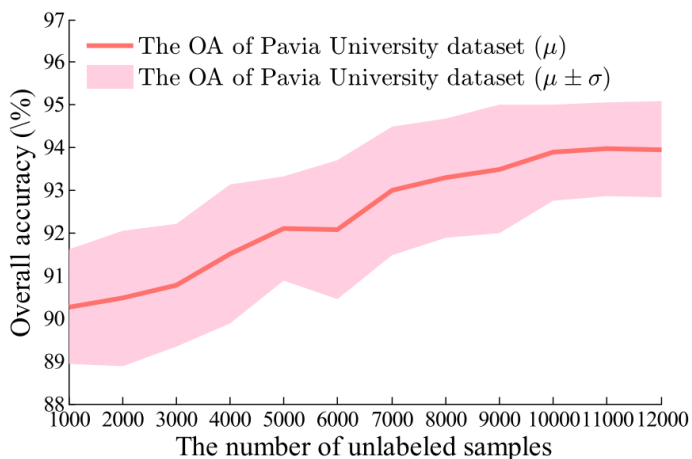


Semi-supervised Learning

- Performance of teacher and student nets over time



- Performance with different numbers of unlabeled samples



Weakly Supervised Learning

- Reduce the annotation burden?



VHR image



Point-level annotations



Dense annotations

Weakly Supervised Learning

- The spatial continuity of ground objects:
Adjacent pixels are likely to belong to the same category

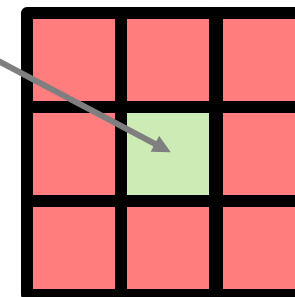


VHR image



Point-level annotations

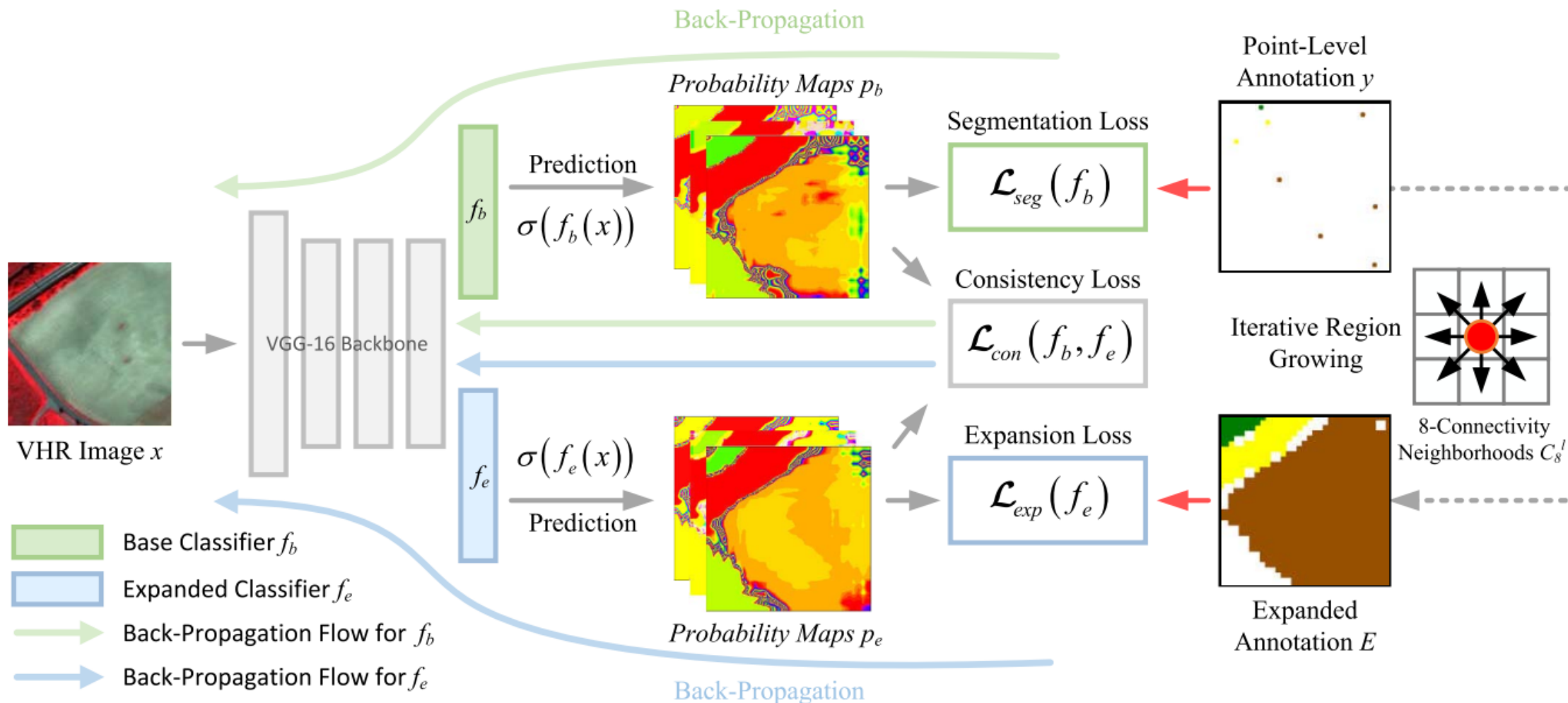
8-connectivity neighborhood



Neighborhood pixels are likely to belong to the grass

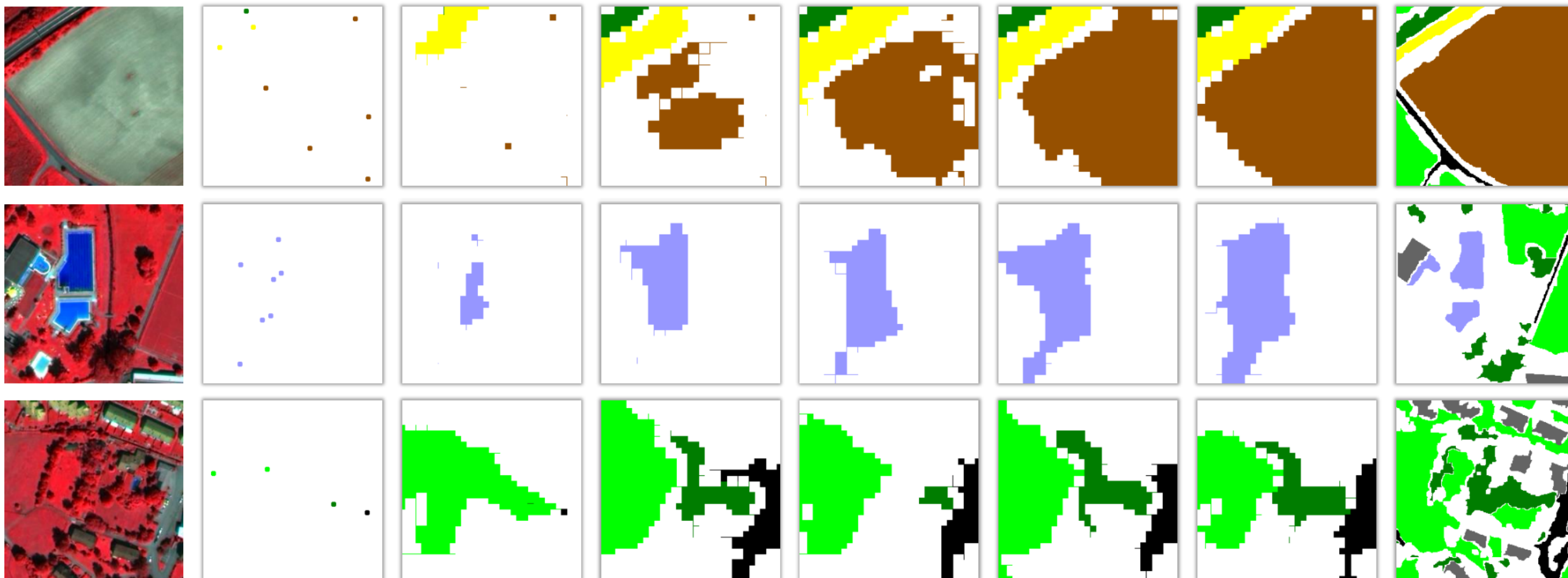
Weakly Supervised Learning

- Consistency-regularized region-growing network



Weakly Supervised Learning

- Dynamically expanded annotations at different iterations



VHR image

Point-level annotations

Iter #100

Iter #200

Iter #300

Iter #400

Iter #500

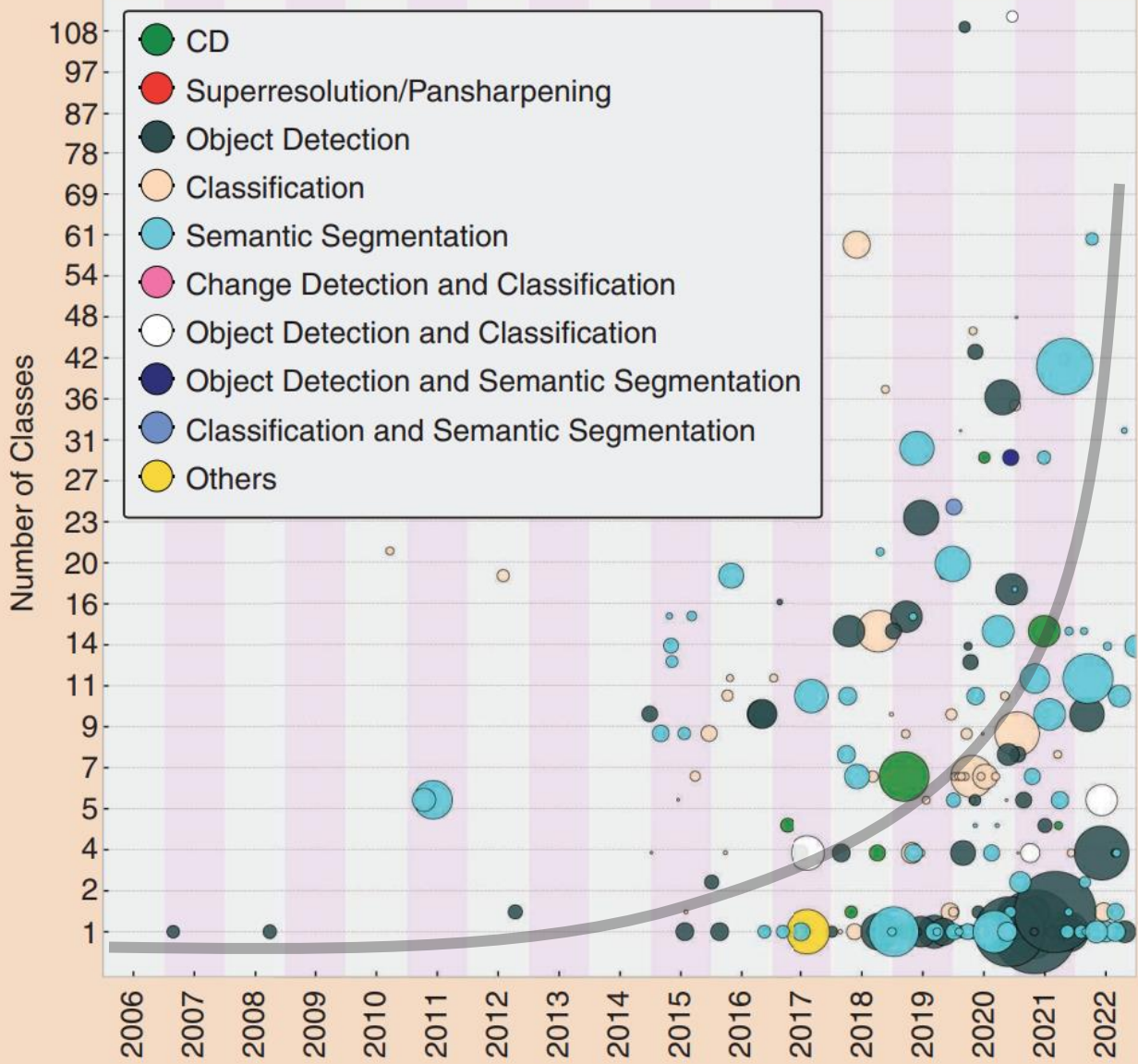
Pixel-wise annotations

AI-Driven Remote Sensing Data Interpretation

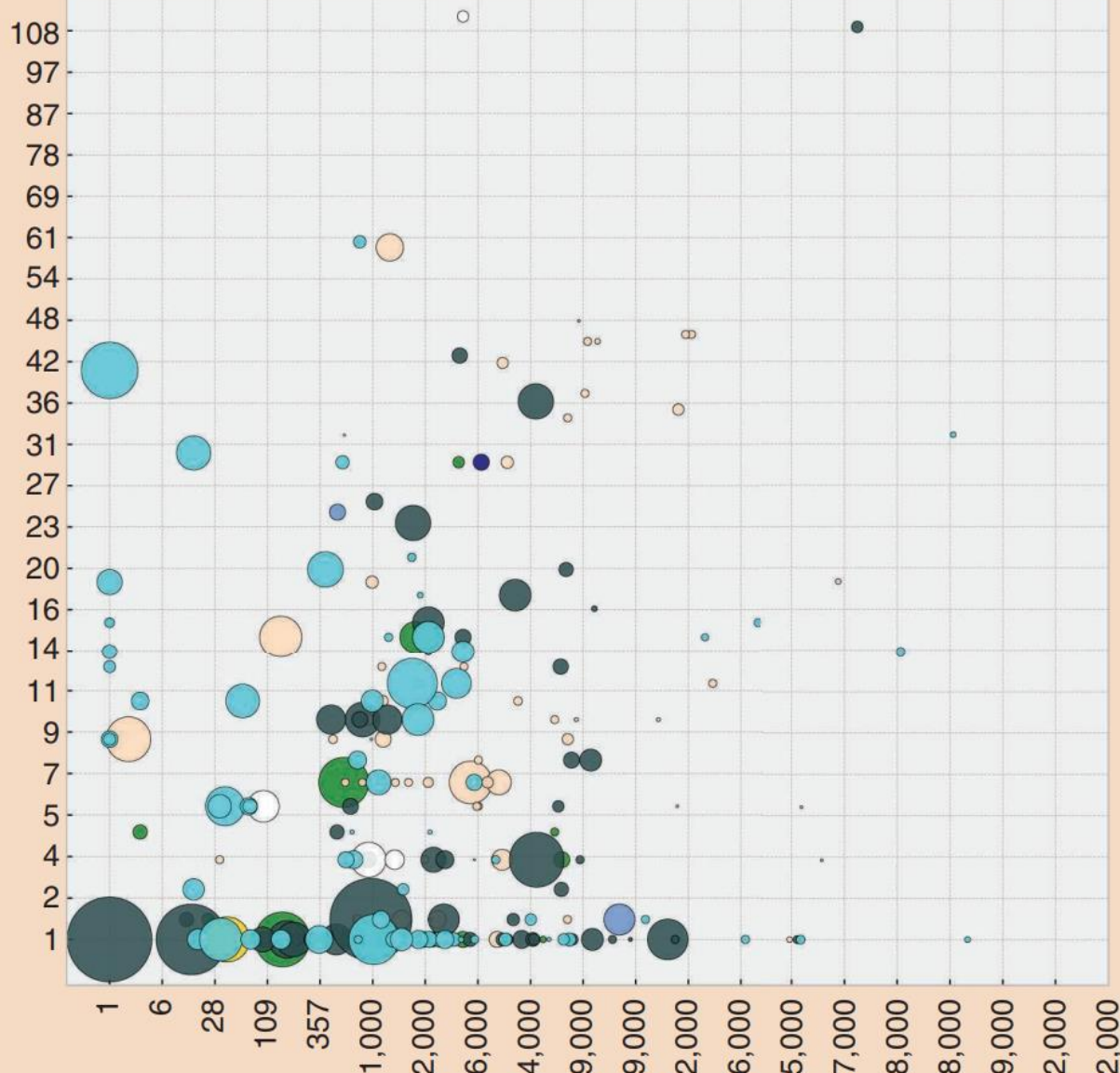
- Challenge: Deep neural networks are **data-hungry**
 - ✓ Developing specially designed machine learning algorithms
 - Unsupervised learning
 - Semi-supervised learning
 - Weakly supervised learning
 -

AI-Driven Remote Sensing Data Interpretation

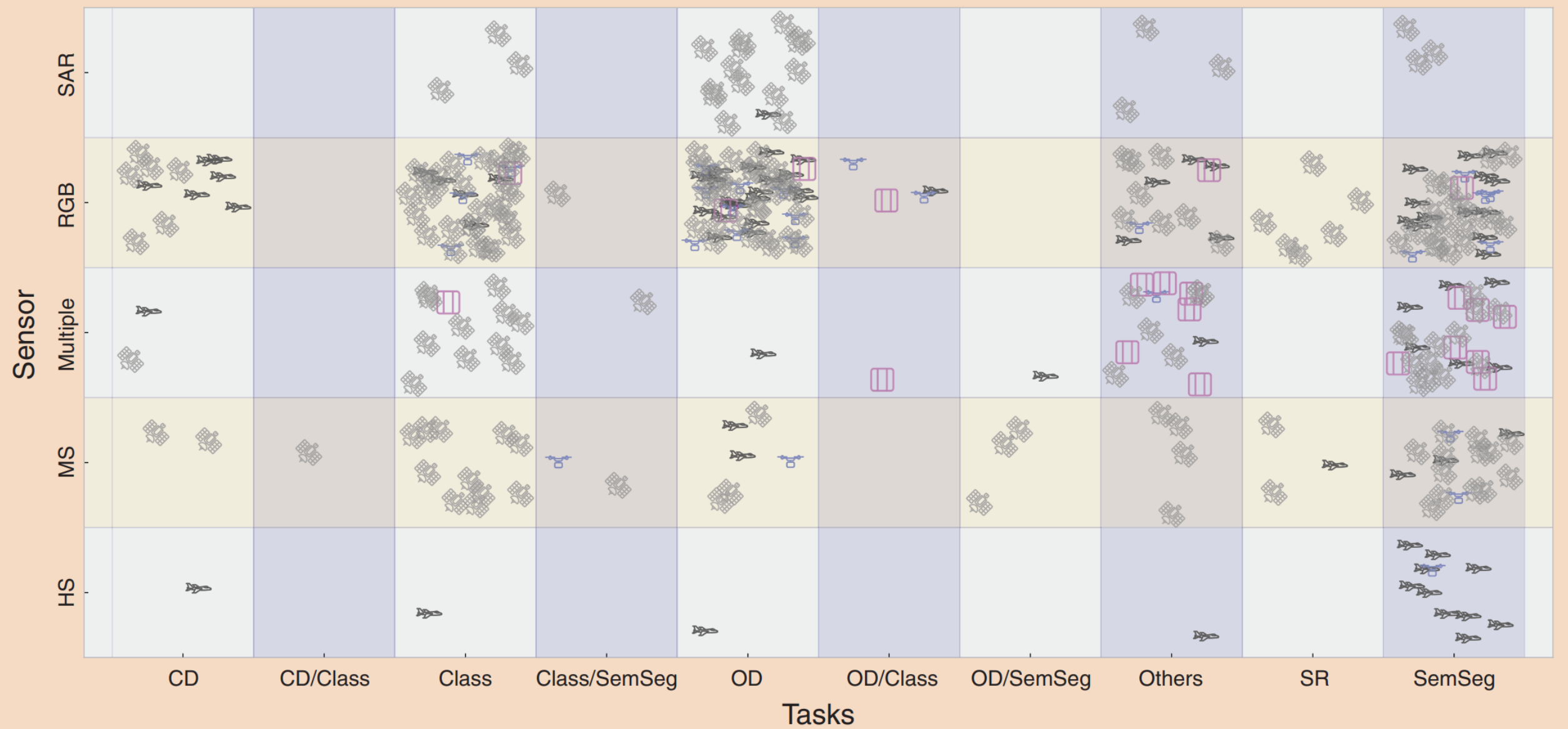
- Challenge: Deep neural networks are **data-hungry**
 - ✓ Developing specially designed machine learning algorithms
 - Unsupervised learning
 - Semi-supervised learning
 - Weakly supervised learning
 -
 - ✓ Collecting high-quality annotated benchmark datasets



Publication Year
(a)



Number of Images
(b)



Data Fusion

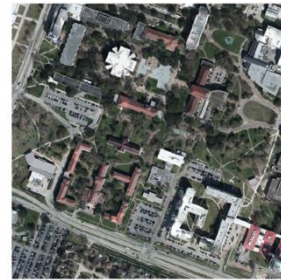
- Advantages of different types of RS data
 - Hyperspectral image: Rich spectral information
 - Very high-resolution image: Precise spatial details
 - LiDAR data: Elevation information

Data Fusion

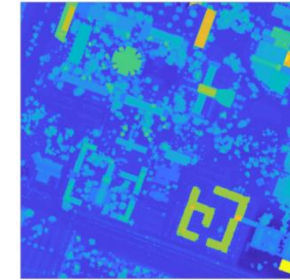
- Advantages of different types of RS data
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HSI



VHRI

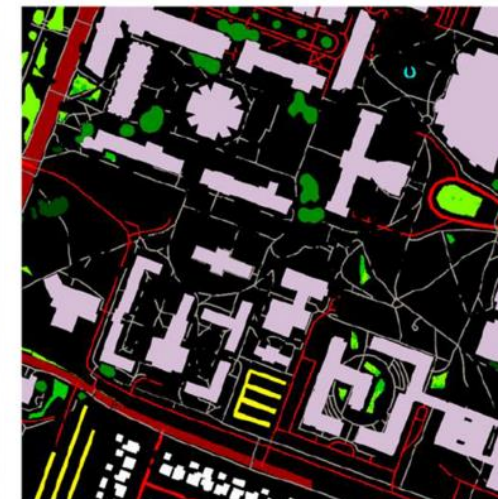
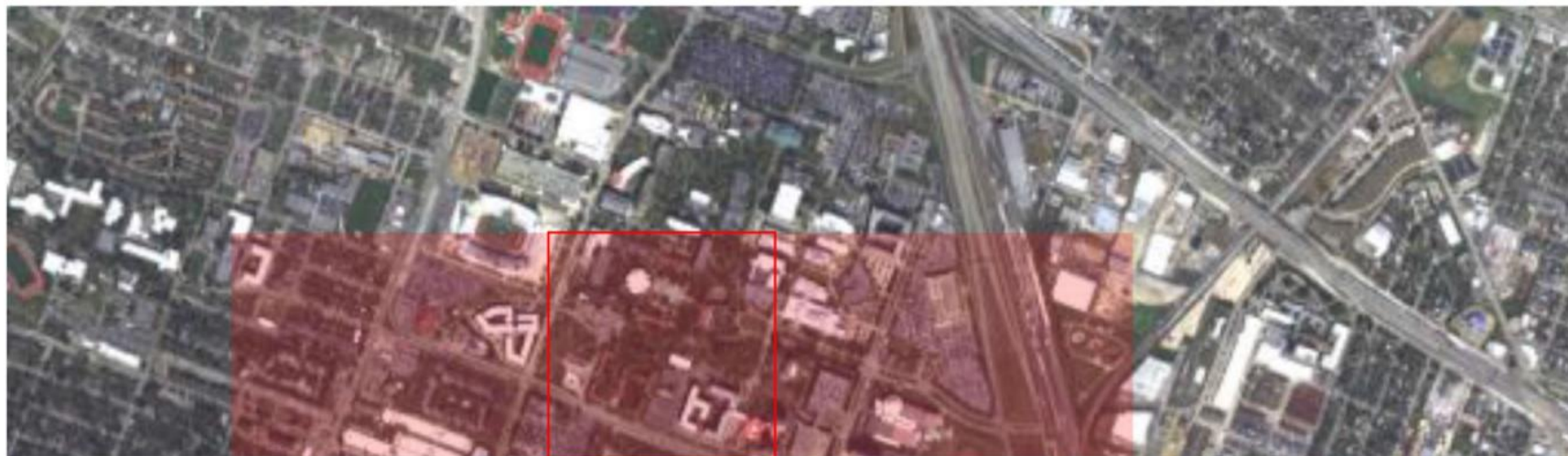


LiDAR



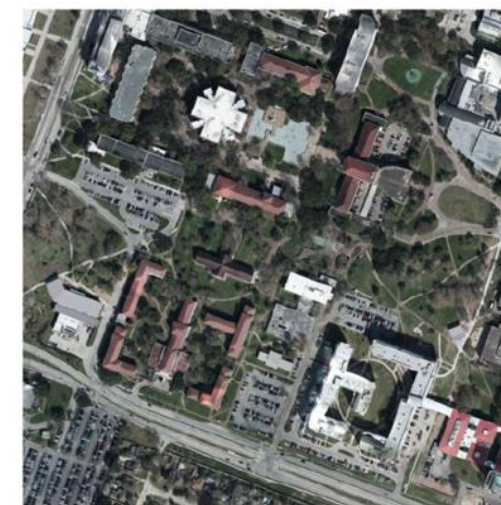
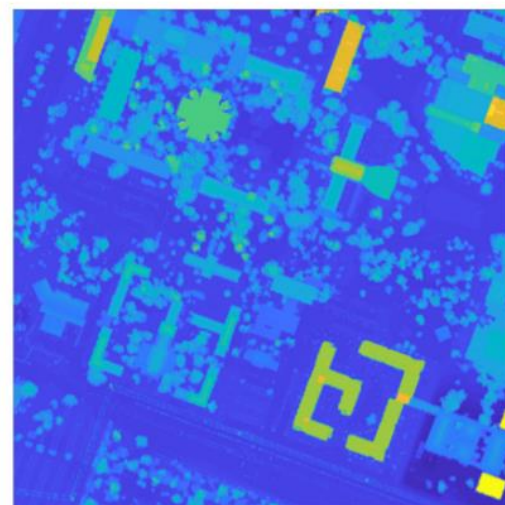
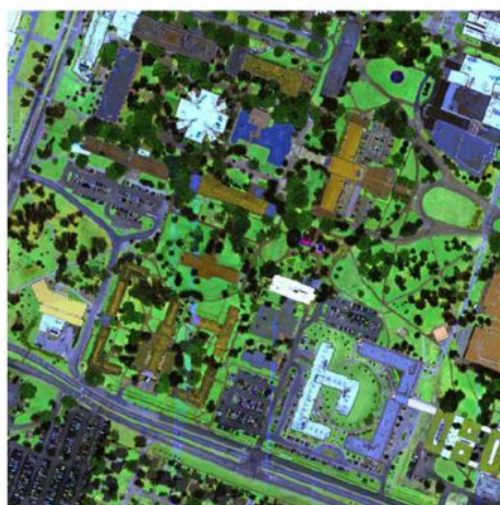
Multi-sensor land cover mapping

Data Fusion



Training (red) and test (entire imagery **except red**) areas

GT



Multispectral LiDAR

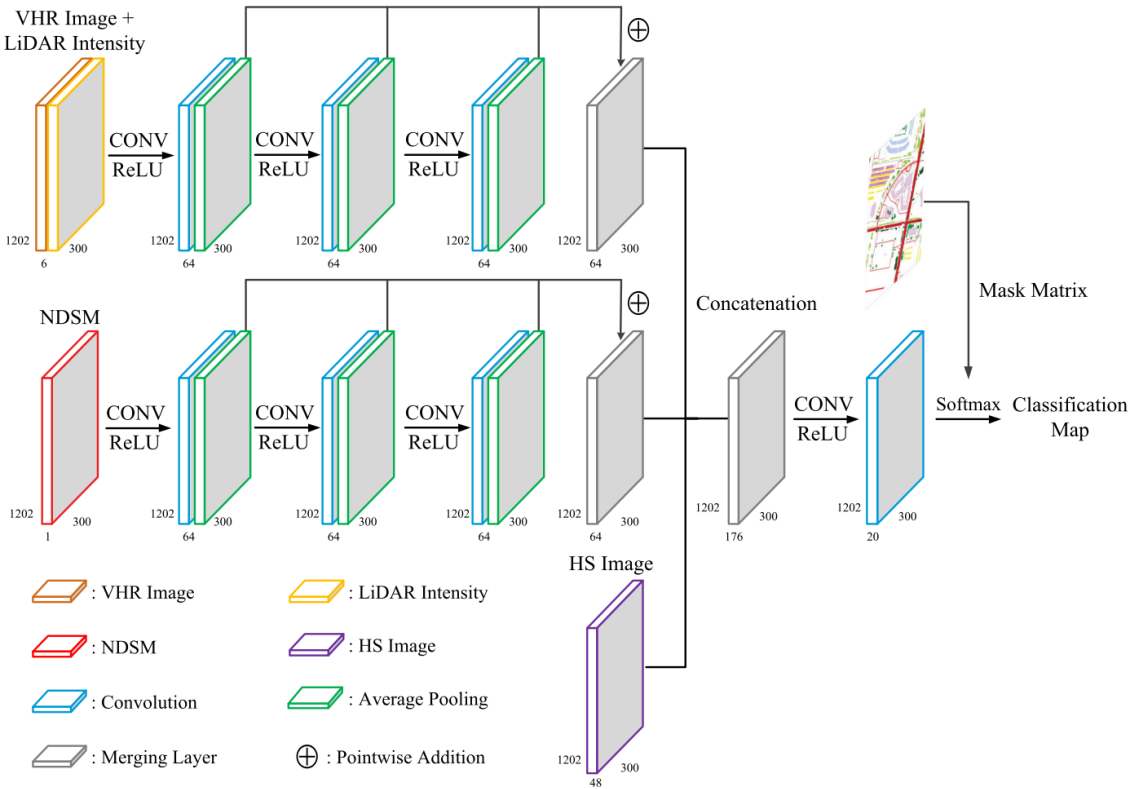
DSM

HSI

VHR

Data Fusion

- End-to-end network

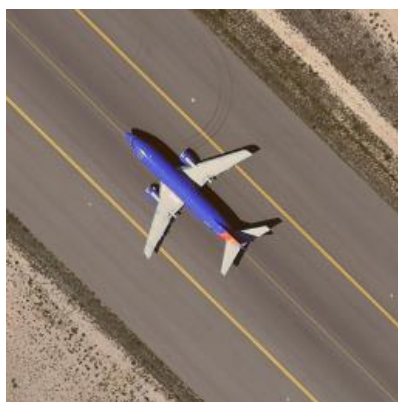


Fusion-FCN

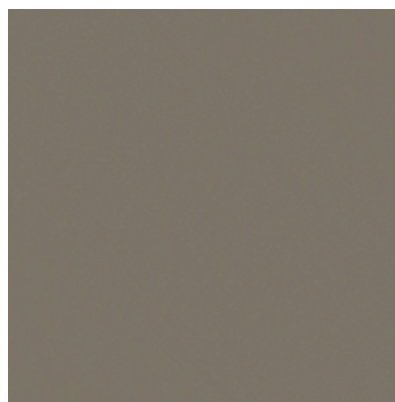
(1st place in IEEE Data Fusion Contest 2018)

AI Security

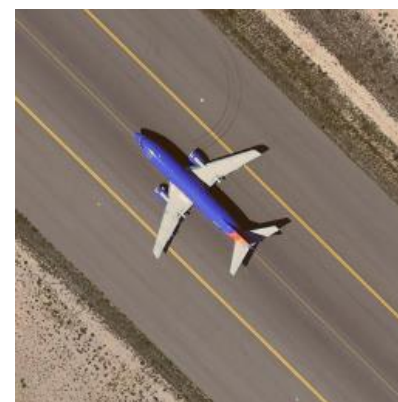
- Are deep neural networks robust to perturbation?



Airplane



Perturbation

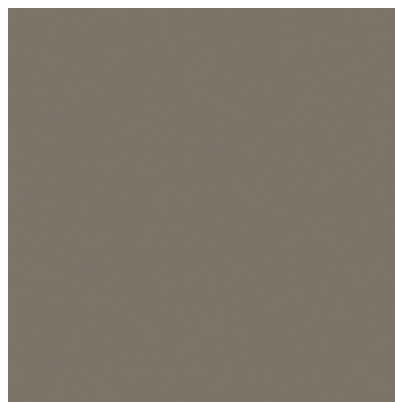


Runway

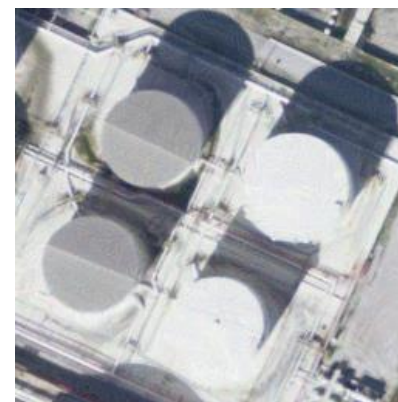
96.56%
confidence



Storage tanks



Perturbation

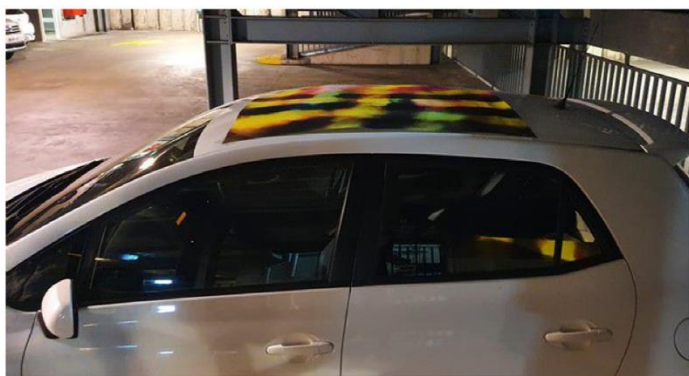


Intersection

99.99%
confidence

AI Security

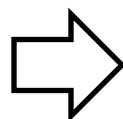
- Are deep neural networks robust to perturbation?



Adversarial patch on the roof of a car



Adversarial patch off-and-around a car

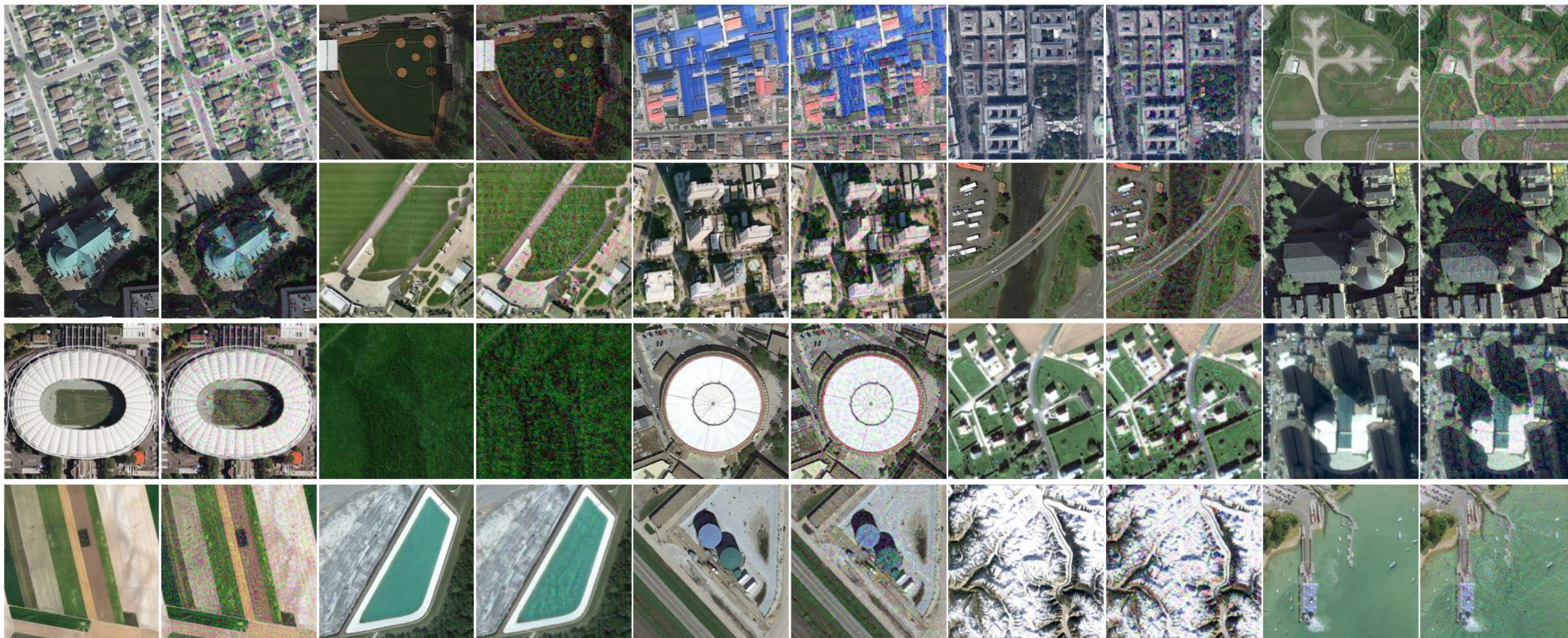


Without adversarial patches



With adversarial patches

UAE-RS Dataset



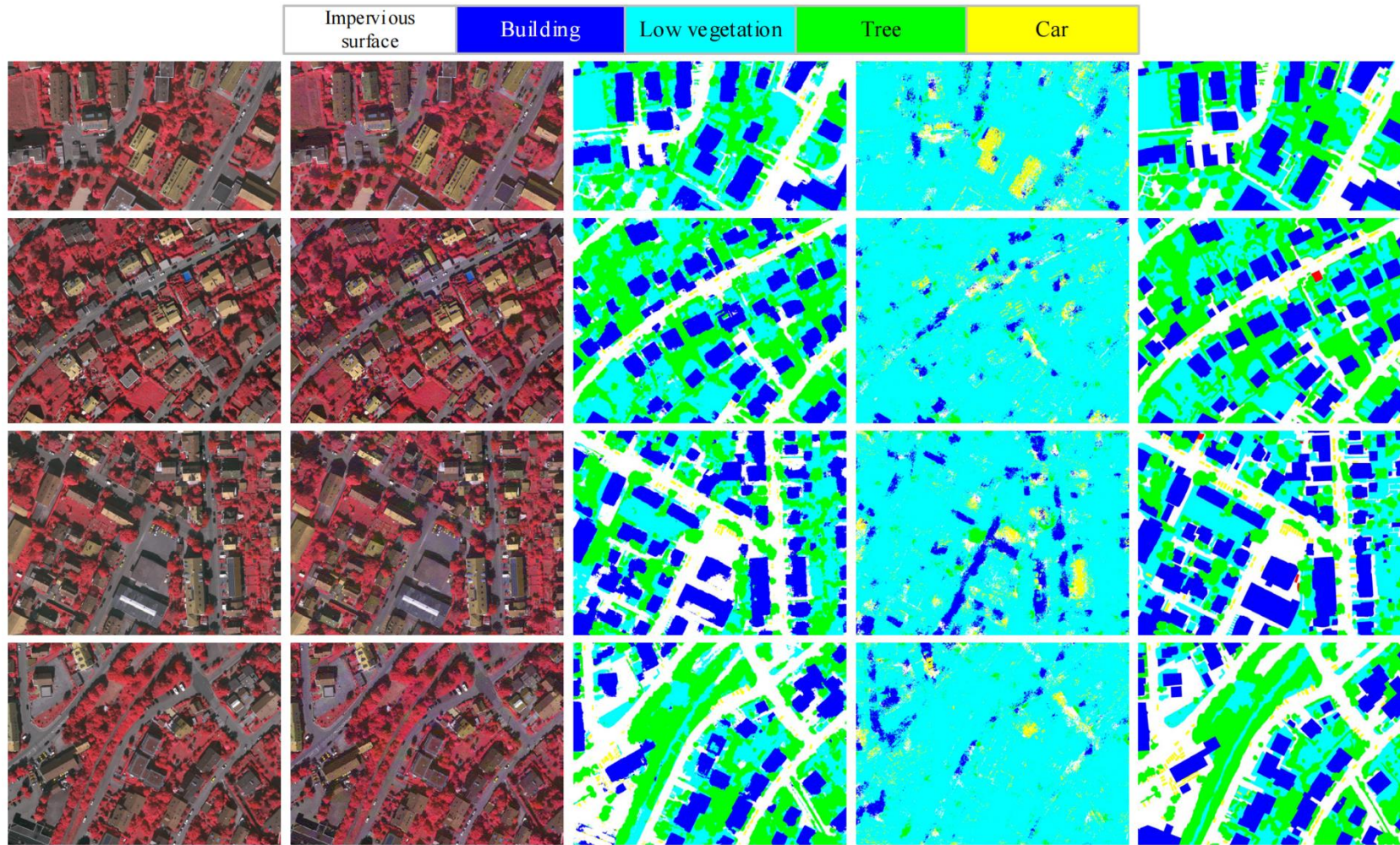
Example images in the AID dataset and the corresponding adversarial examples in the UAE-RS dataset

Quantitative Results on UAE-RS Dataset

QUANTITATIVE SCENE CLASSIFICATION RESULTS OF DIFFERENT DEEP NEURAL NETWORKS ON THE CLEAN AND UAE-RS TEST SETS.

Model	UCM			AID		
	Clean Test Set	UAE-RS Test Set	OA Gap	Clean Test Set	UAE-RS Test Set	OA Gap
AlexNet [48]	90.28	30.86	-59.42	89.74	18.26	-71.48
VGG11 [56]	94.57	26.57	-68.00	91.22	12.62	-78.60
VGG16 [56]	93.04	19.52	-73.52	90.00	13.46	-76.54
VGG19 [56]	92.85	29.62	-63.23	88.30	15.44	-72.86
Inception-v3 [57]	96.28	24.86	-71.42	92.98	23.48	-69.50
ResNet18 [49]	95.90	2.95	-92.95	94.76	0.02	-94.74
ResNet50 [49]	96.76	25.52	-71.24	92.68	6.20	-86.48
ResNet101 [49]	95.80	28.10	-67.70	92.92	9.74	-83.18
ResNeXt50 [58]	97.33	26.76	-70.57	93.50	11.78	-81.72
ResNeXt101 [58]	97.33	33.52	-63.81	95.46	12.60	-82.86
DenseNet121 [50]	97.04	17.14	-79.90	95.50	10.16	-85.34
DenseNet169 [50]	97.42	25.90	-71.52	95.54	9.72	-85.82
DenseNet201 [50]	97.33	26.38	-70.95	96.30	9.60	-86.70
RegNetX-400MF [51]	94.57	27.33	-67.24	94.38	19.18	-75.20
RegNetX-8GF [51]	97.14	40.76	-56.38	96.22	19.24	-76.98
RegNetX-16GF [51]	97.90	34.86	-63.04	95.84	13.34	-82.50

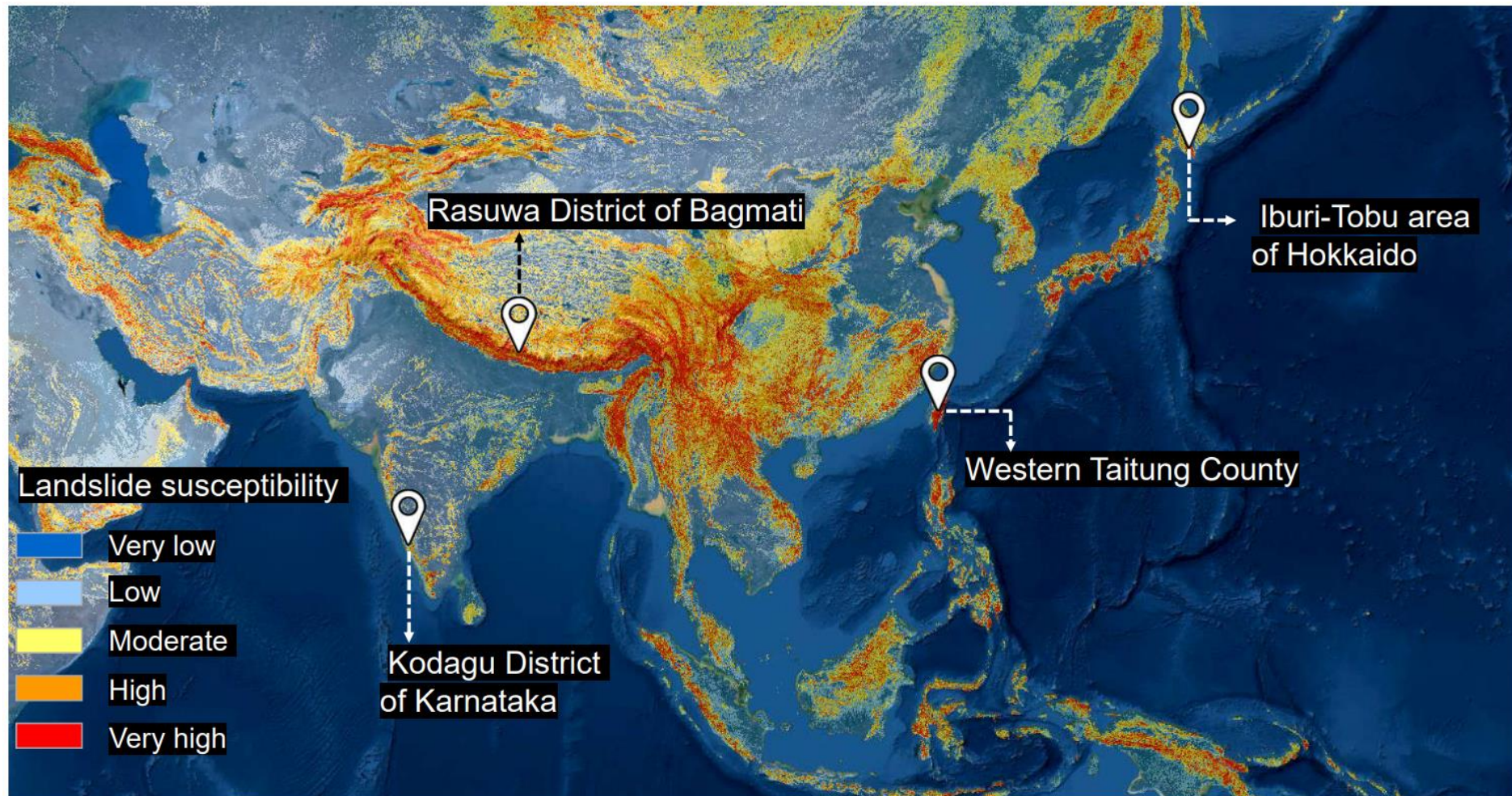
UAE-RS Dataset



Qualitative results of the black-box adversarial attacks from FCN-8s → SegNet on the Vaihingen dataset

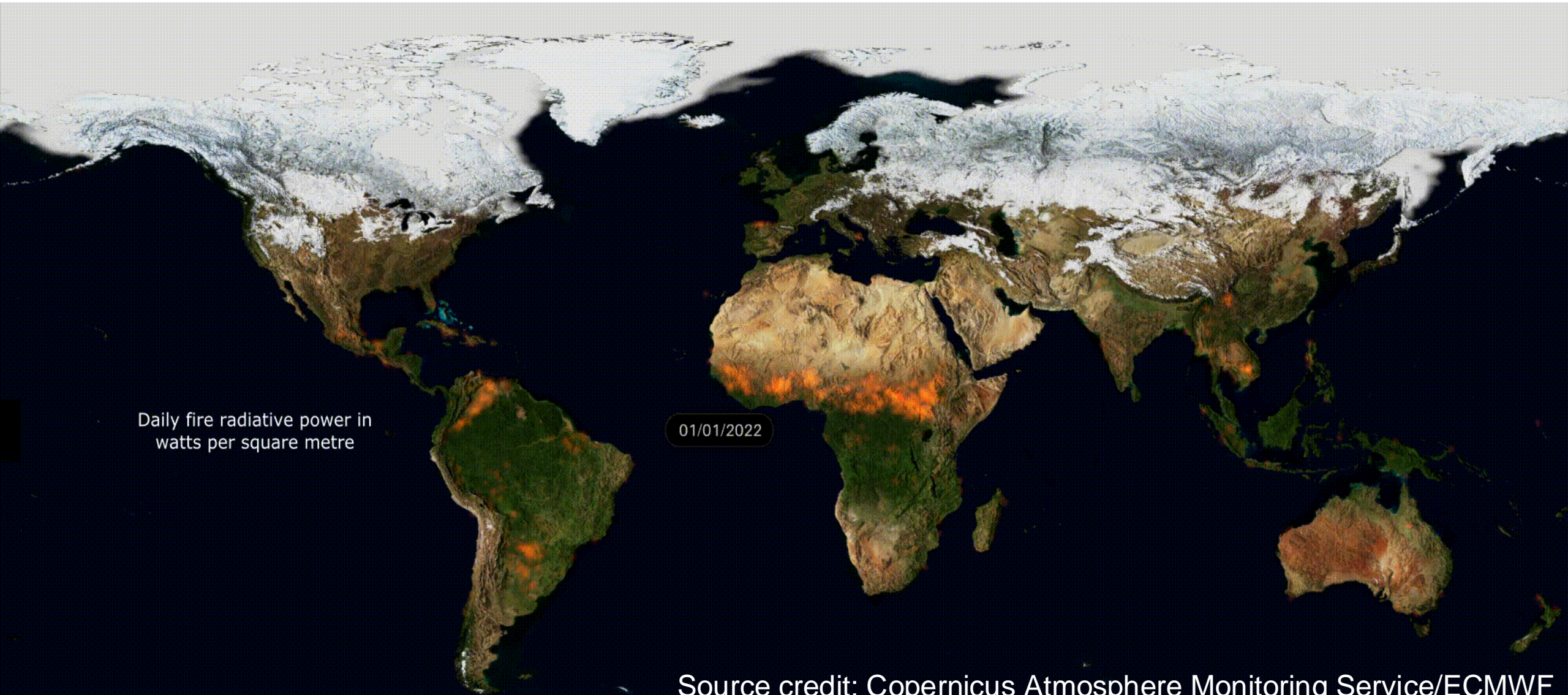
Application

- AI for environmental monitoring

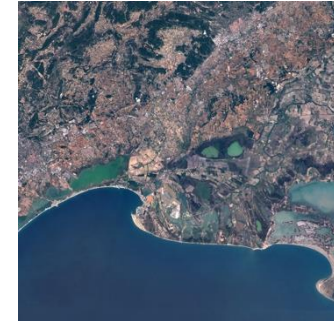
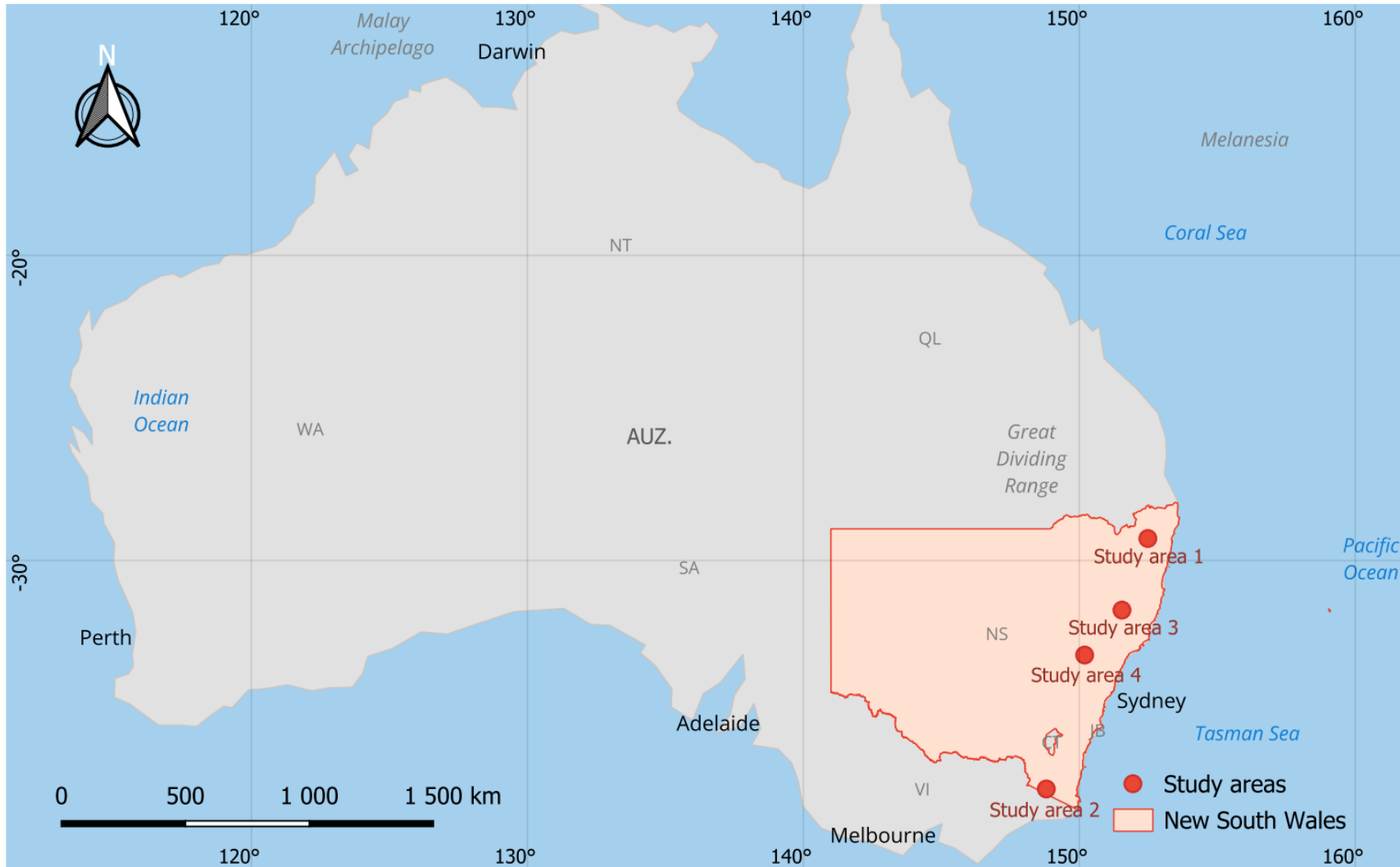


Application

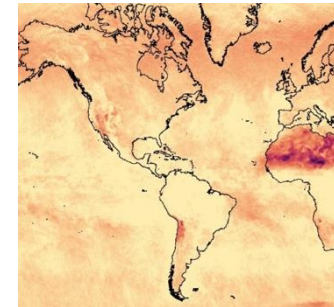
- Satellite remote sensing for global wildfire observation



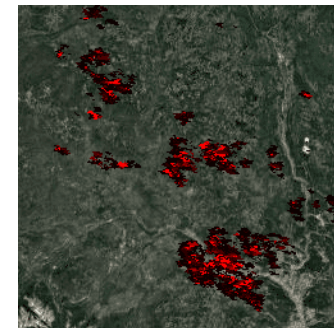
Application



Sentinel-2



Sentinel-5P



MOD14A1

Four bushfires happened in the 2019–2020 Australian bushfire season

Preliminary Experiments

- Input Strategies

RGB composite: B4, B3, B2.

SWIR composite: B12, B8, B4.

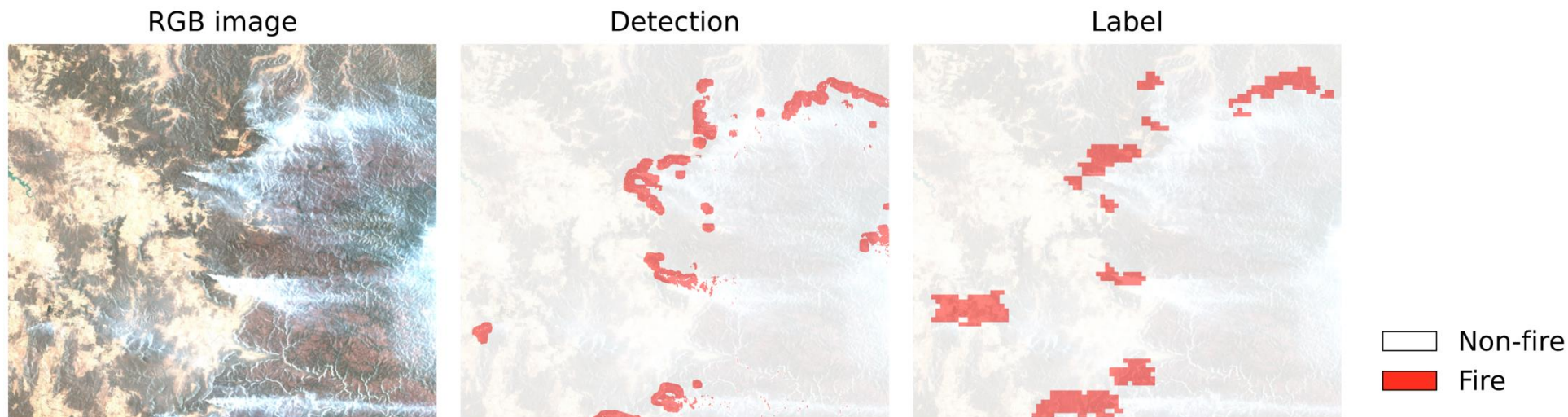
NBR composite: NBR, B4, B3.

NDVI composite: NDVI, B4, B3.

RGB+SWIR+NBR+NDVI: B4, B3, B2, B12, NBR, NDVI.

Vanilla input: B1, B2, B3, . . . , B10, B11, B12.

Input strategies	Precision	Recall	F1 score
RGB composite	11.8	18.3	14.4 (*)
+aerosol	14.7	21.3	17.4 \uparrow 3.0
SWIR composite	43.9	20.5	27.9 (*)
+aerosol	39.7	21.8	28.1 \uparrow 0.2
NBR composite	26.0	24.1	25.1 (*)
+aerosol	20.6	23.9	22.1 \downarrow 3.0
NDVI composite	13.4	13.0	13.2 (*)
+aerosol	11.4	23.1	15.2 \uparrow 2.0
RGB+SWIR+NBR+NDVI	38.6	17.1	23.7 (*)
+aerosol	35.5	19.1	24.8 \uparrow 1.1
Vanilla input	22.4	29.5	25.5 (*)
+aerosol	37.4	20.1	26.1 \uparrow 0.6



Wildfire detection result on the test set. The input patches are concatenated to reconstruct the complete image tile

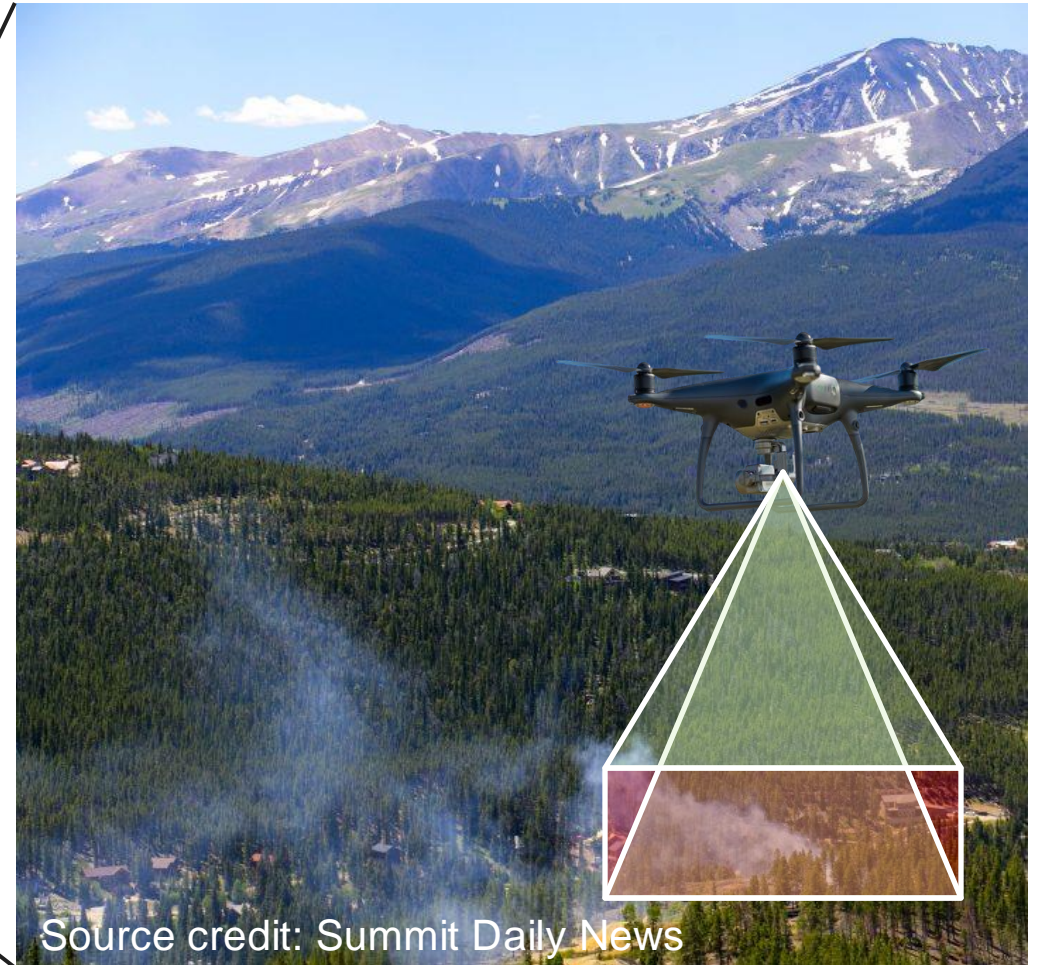
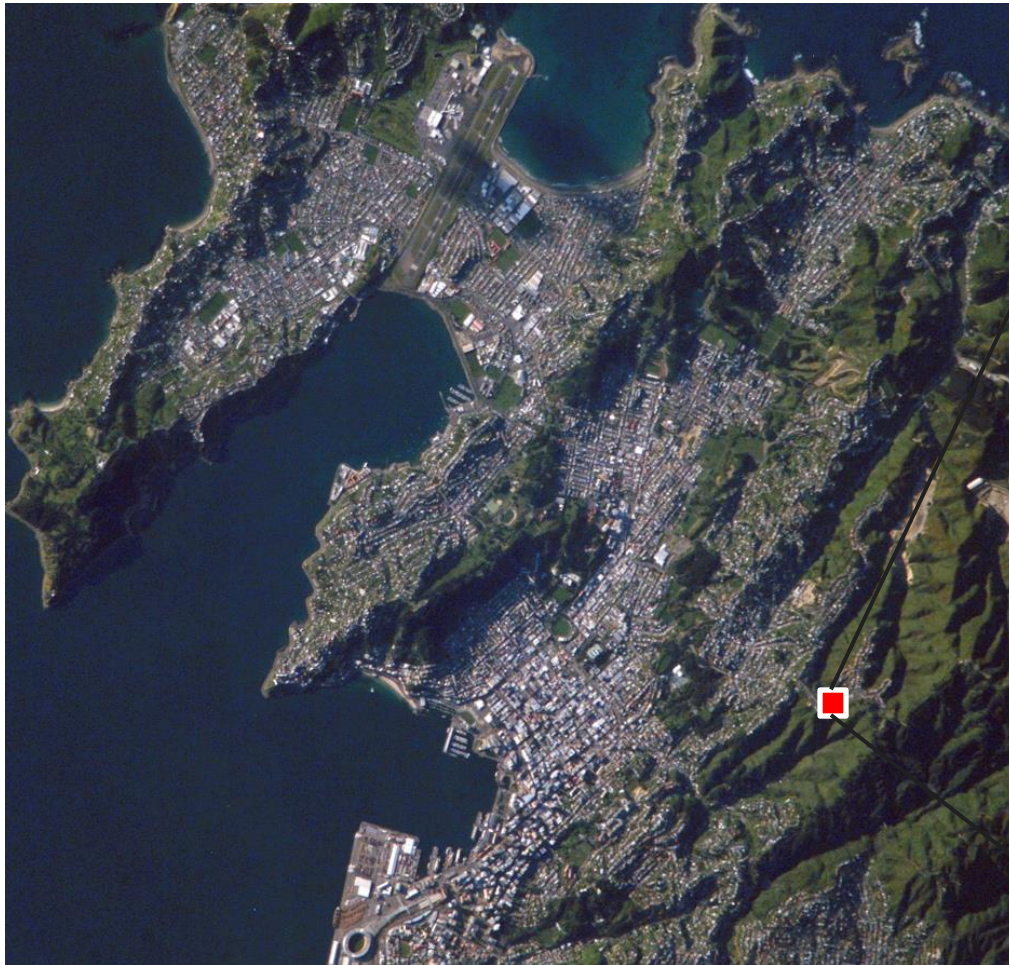
Application

- Satellite remote sensing alone is insufficient for early local fire detection



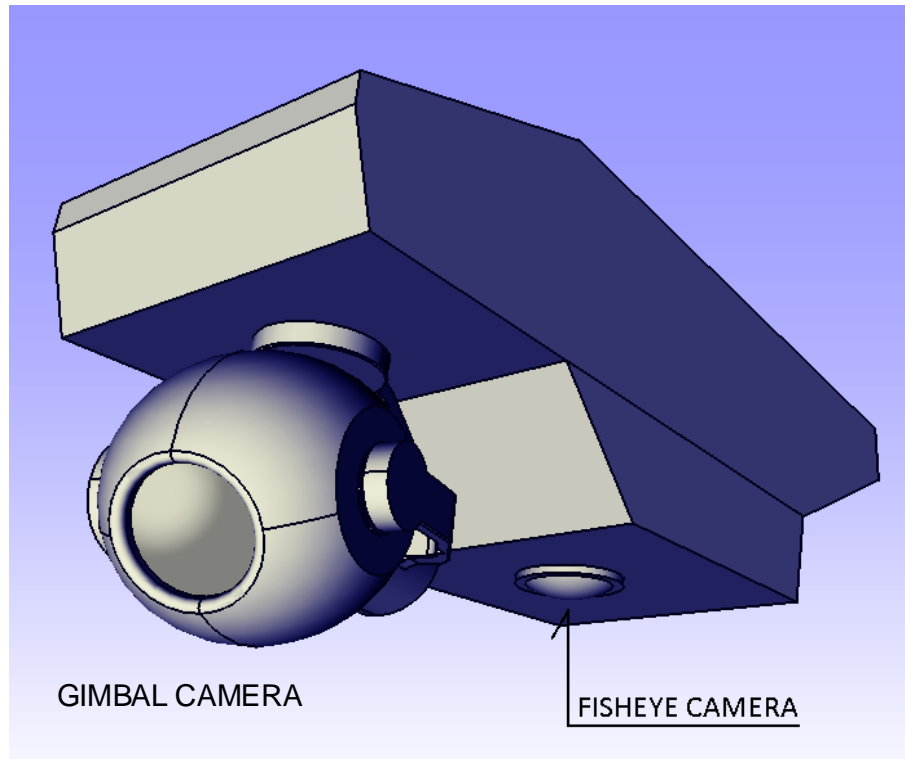
Application

- Satellite remote sensing alone is insufficient for early local fire detection



Dual-Camera AI

- Real-time autonomous wildfire detection system with dual-camera AI



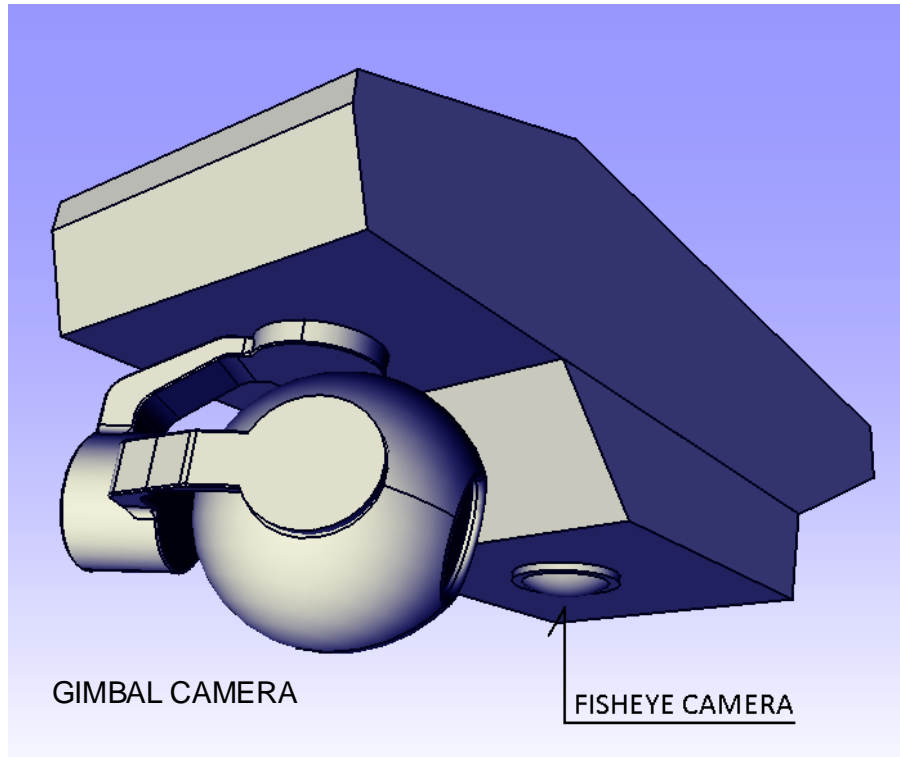
Dual camera system



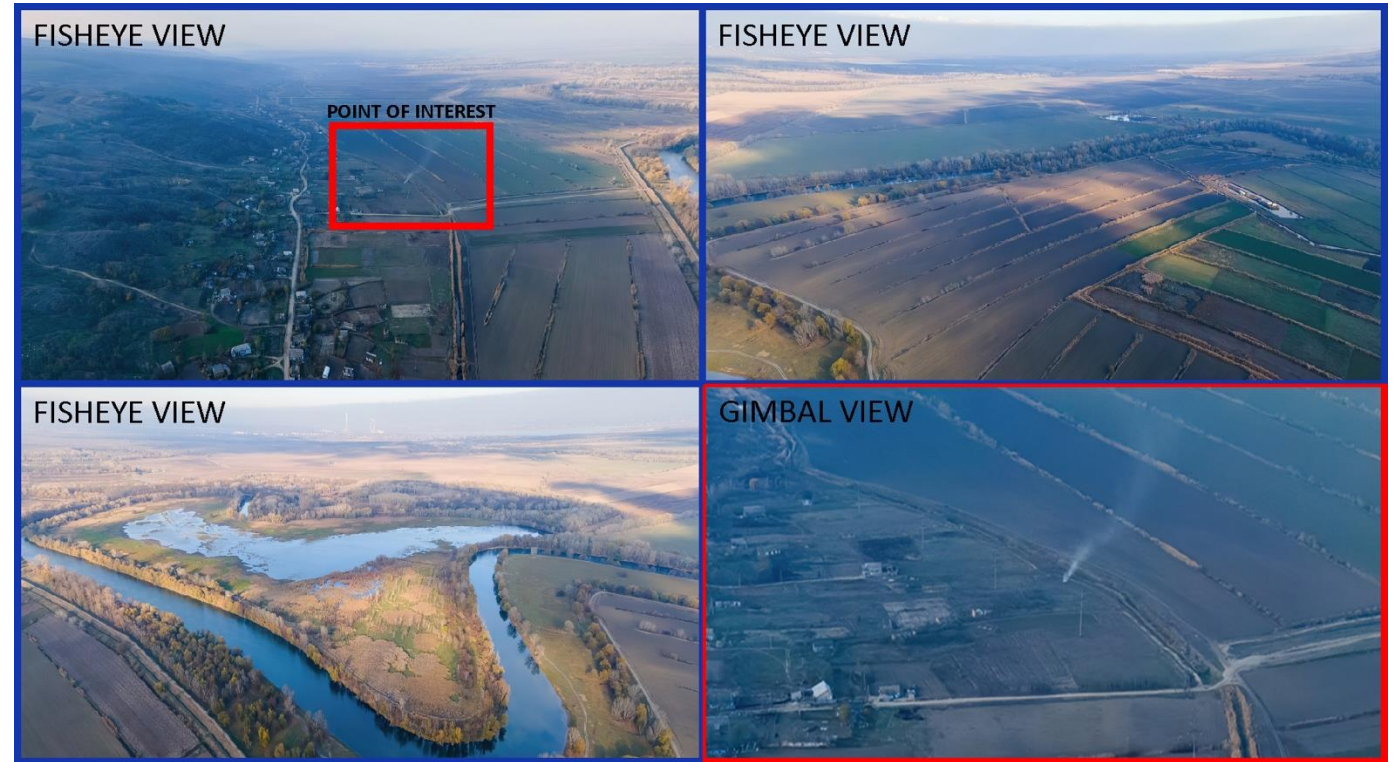
The camera interface highlights regions of interest via a user or a **learnable detector**

Dual-Camera AI

- Real-time autonomous wildfire detection system with dual-camera AI



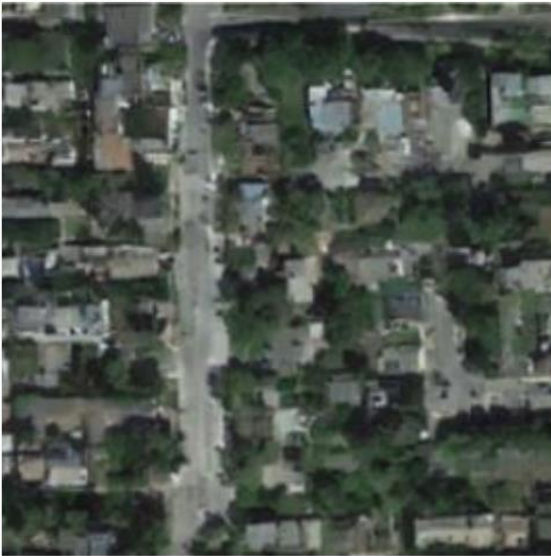
The gimbal panned to zoom in on the region of interest



The user receives a more detailed picture of the region of interest

Future Directions

- Vision and language for remote sensing
 - ✓ Remote sensing image captioning, text to image generation...



Many green trees and buildings are in a dense residential area



Many people are in a piece of yellow beach near an ocean



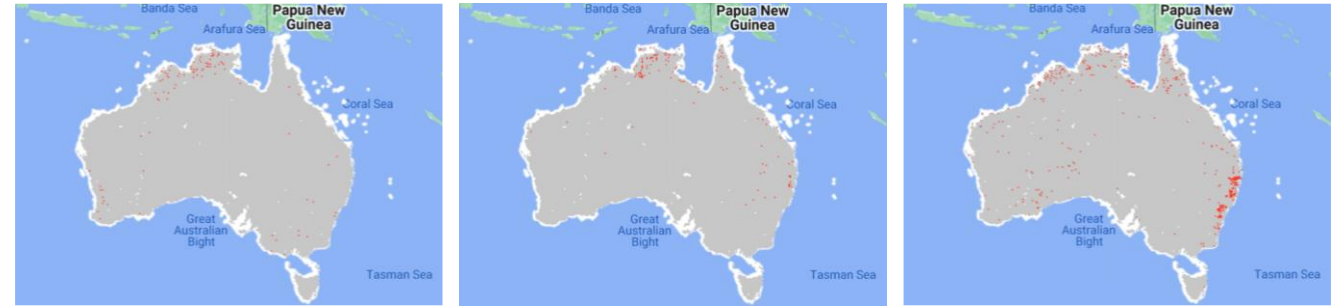
Some white storage tanks are in a piece of bareland



The polygonal pond is surrounded by tiny villas

Future Directions

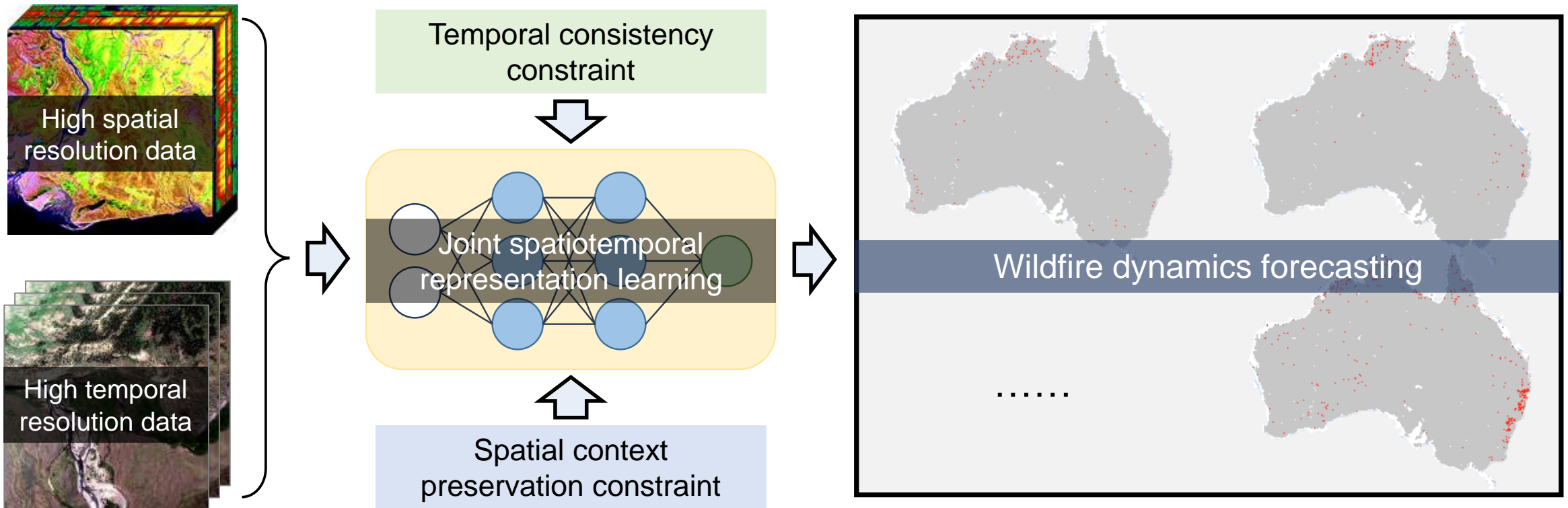
- Earth dynamics modeling



(a) April 2019 – June 2019

(b) July 2019 – September 2019

(c) October 2019 – December 2019



Remote Sensing Group



Leif Haglund
Strategic Advisor (Maxar)
Adjunct Professor (CVL)



Amanda Berg
Research Developer (Maxar)
Adjunct Assistant Lecturer (CVL)



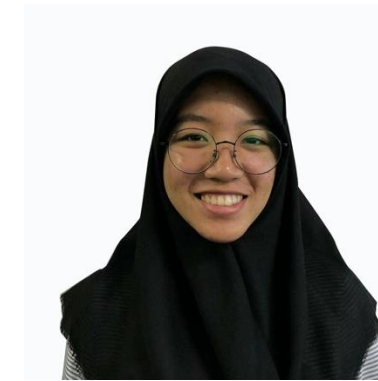
Yonghao Xu
Assistant Professor (CVL)



Justus Karlsson
PhD Student (CVL)



Gulnaz Zhambulova
PhD Student (CVL)



Aprilia Nidia Rinasti
PhD Student (CVL)

Thank You!

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Linköping University

2024-09-16